

# Relaxations for Production Planning Problems with Increasing Byproducts

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Joint work with  
Jeffrey Linderoth and James R. Luedtke

## One slide summary

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### ▶ **Performance evaluation**



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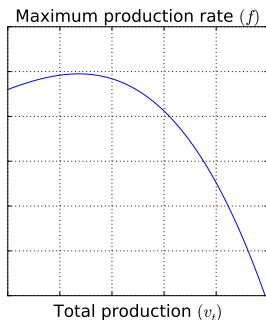
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- ▶ **Continuous** decisions determine the **production profile** evaluated by production functions  $f(\cdot)$  and  $g_p(\cdot)$ .

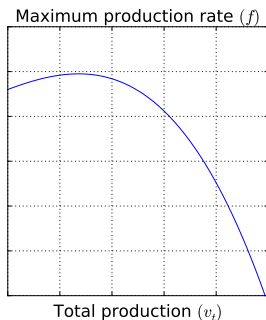
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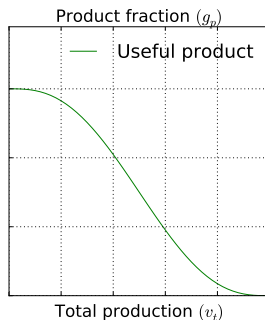
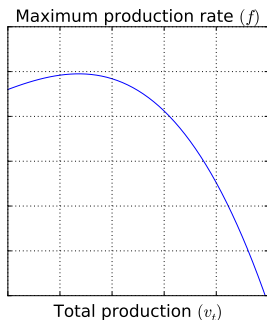
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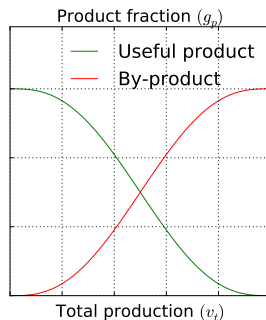
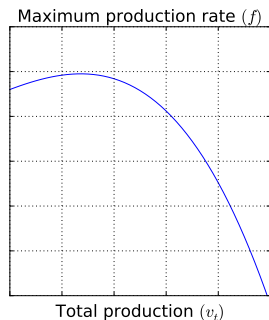
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Production profiles are **active** only after the **start time**  $z(t)$

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Past models have proposed a natural discretization of this continuous time model.

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- $z_t$  Facility on/off decision variable.

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How much product is produced up to time  $t$ ?

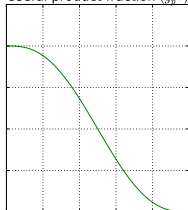
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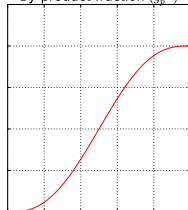
$$w_{p,t} \stackrel{\text{def}}{=} \sum_{s \leq t} y_{p,s}$$

Useful product fraction ( $g_p^+$ )



Total Production ( $v_t$ )

By-product fraction ( $g_p^-$ )



Total Production ( $v_t$ )

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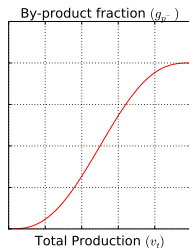
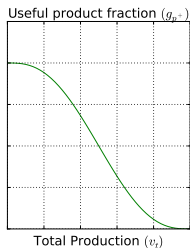
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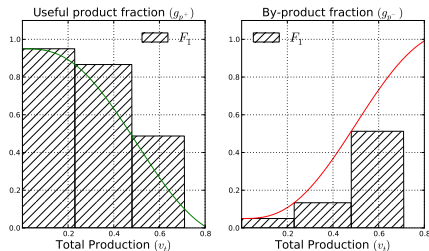
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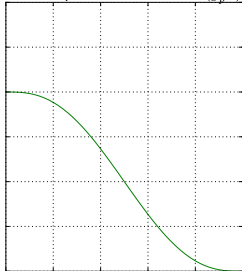
## Alternate formulation



### Key Idea

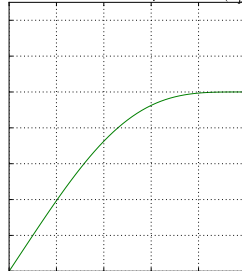
- ▶ Integral of a **non-increasing** function is **concave**.

Useful product fraction ( $g_p^+$ )



Total production ( $v_t$ )

Cumulative useful product ( $h_p^+$ )



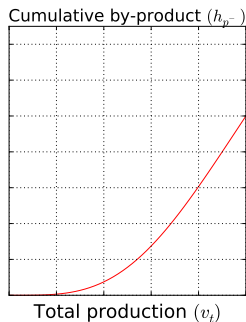
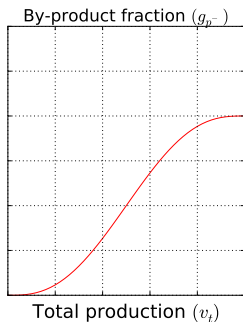
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### Key Idea

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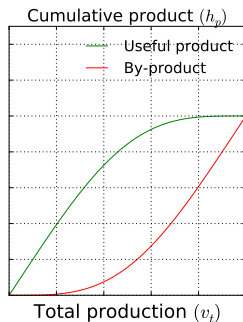
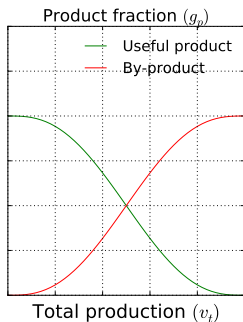


## Alternate formulation



### Key Idea

- ▶ Integral of a **non-increasing** function is **concave**.
- ▶ Integral of a **non-decreasing** function is **convex**.
- ▶ Lets deal with  $h_p$  instead of  $g_p$ !





## Comparing formulations

What have we done so far ?

---

### Formulation F<sub>1</sub>

$$v_t = \sum_{s=0}^t x_s$$

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# Comparing Formulations

Which formulation is **better**?

---

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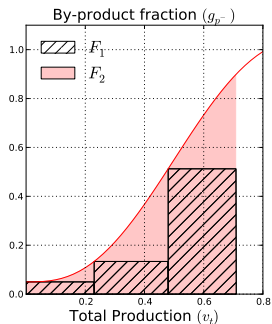
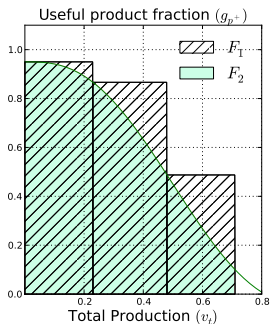
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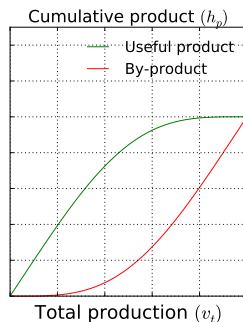
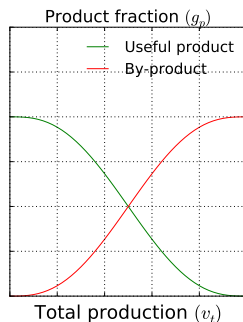




## Comparing Formulations

Which formulation is **better**?

- ▶  $F_2$  is a more **accurate** formulation of CNT than  $F_1$ .
- ▶  $F_2$  is **computationally better** because it deals with **convex** functions while  $F_1$  deals with **bilinear** terms.



## MIP Approximation & Relaxations

# Approximations & Relaxations



## Mixed Integer Non-Linear Programs (MINLP)

... are slow and hard!

# Approximations & Relaxations



## Mixed Integer Non-Linear Programs (MINLP)

... are slow and hard!

But...there is hope

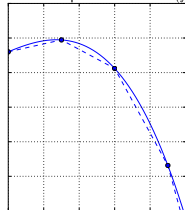
We **only** need to approximate or relax **univariate** convex and concave functions.

# Approximations & Relaxations I

## Piecewise Linear Approximation (PLA)

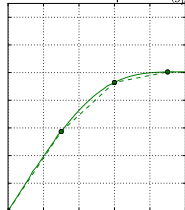
**Approximate** all the nonlinear production functions with piecewise linearizations.

Maximum production rate ( $f$ )



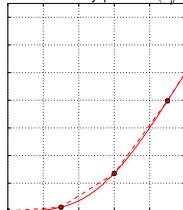
Total production ( $v_t$ )

Cumulative useful product ( $g_{p^+}$ )



Total production ( $v_t$ )

Cumulative by-product ( $h_{p^-}$ )



Total production ( $v_t$ )

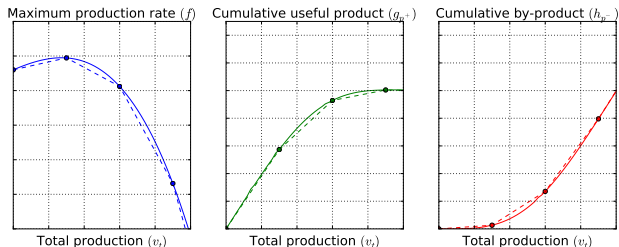
# Approximations & Relaxations I

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Approximate all the nonlinear production functions with piecewise linearizations.

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- 'Close' to a feasible solution of the MINLP formulation.

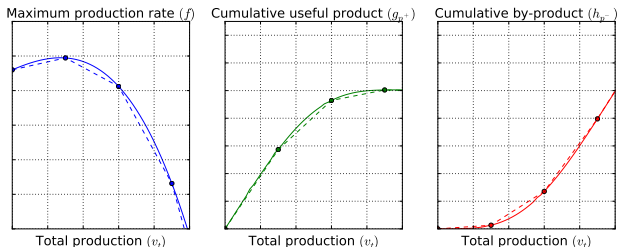


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**Approximate** all the nonlinear production functions with piecewise linearizations.

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  - ▶ Introduces additional SOS2 variables to branch on.

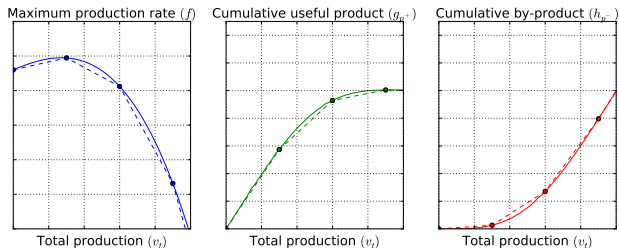


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- ▶ **Cons**
  - ▶ Introduces additional SOS2 variables to branch on.
  - ▶ **NOT** a relaxation of the original formulation.





# Piecewise Linear Approximation (PLA)

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$$v_t = \sum_{s=0}^t x_s$$

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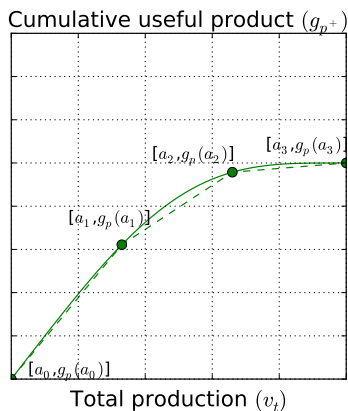
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$$\{\lambda_{t,o} | o \in \mathcal{O}\} \in \text{SOS2}$$

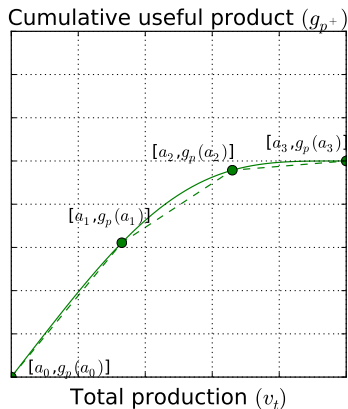
## Specially ordered sets (SOS)



Approximating  $g_p(v_t)$

$$g_p(v_t) \approx \sum_{o \in \mathcal{O}} \lambda_{t,o} g_p(a_o)$$

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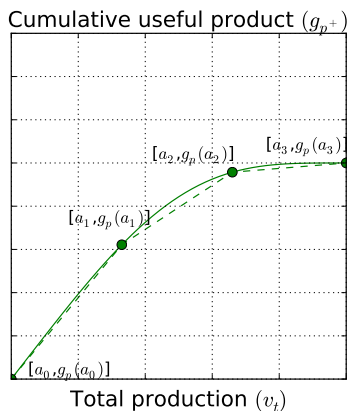


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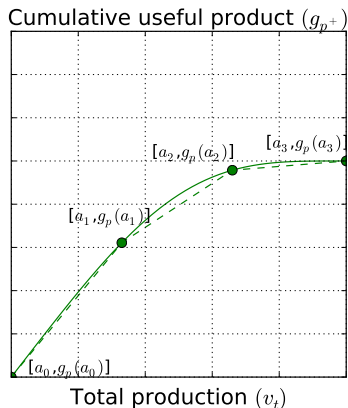
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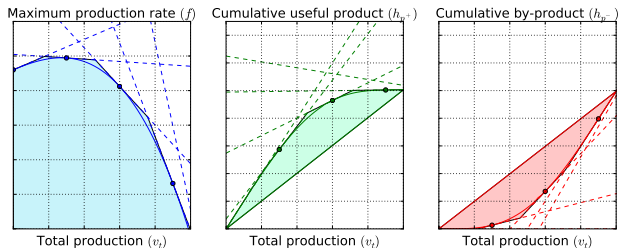
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# Approximations & Relaxations II

## Secant Relaxation (1-SEC)

**Relax** all the nonlinear production functions using inner and outer approximations.



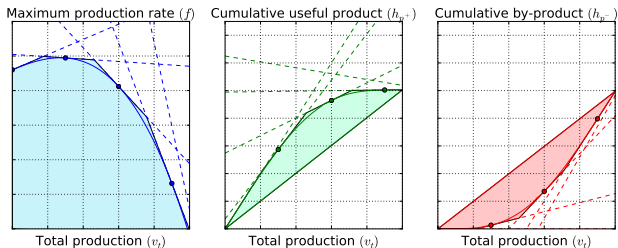
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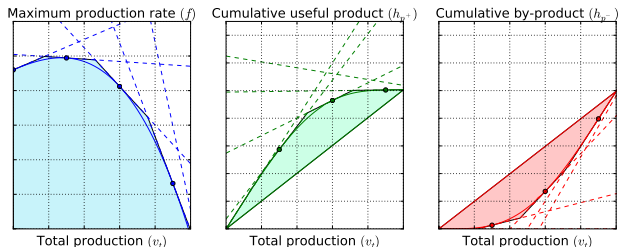


## Approximations & Relaxations II

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- ▶ **Pros**
  - ▶ **Relaxation** of the original formulation.
  - ▶ Does **NOT** introduce additional SOS2 variables.
- ▶ **Cons**
  - ▶ May not be 'close' to a feasible solution of the MINLP formulation.



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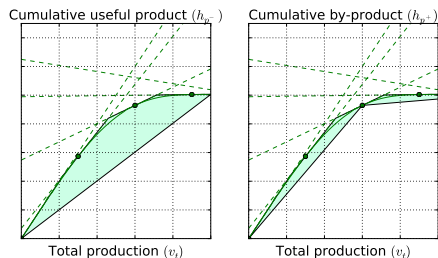
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## Multiple Secant Relaxation (k-SEC)

**Relax** all the nonlinear production functions using inner and outer approximations but use multiple secants instead of a just a single one.





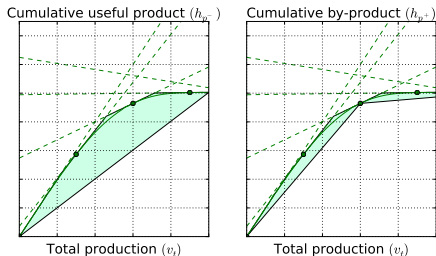
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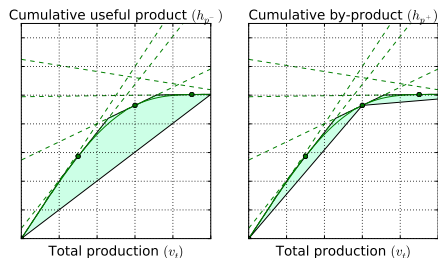


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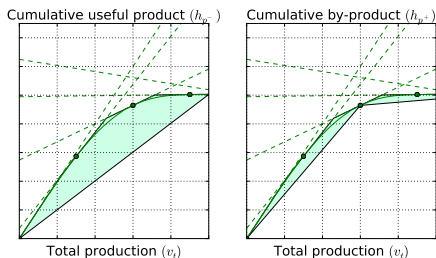
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# Trix

SOS2/Hull binary trick

## Key Idea

- ▶ Production functions are positive **only** if the facility is **open**.
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### Stronger Formulation...

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# Performance Evaluation

# Experiments

## Goals

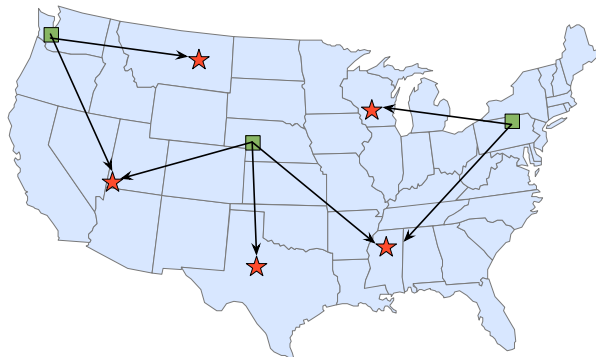
- ▶ Impact on formulation **accuracy** in going from  $F_1$  to  $F_2$
- ▶ Impact in **solution time** in going from  $F_1$  to  $F_2$  as solved by our models.
- ▶ Impact of stronger formulations on solving the MIP approximation/relaxations.

## Sample Application

**Transportation problem** with production facilities manufacturing products for customers.

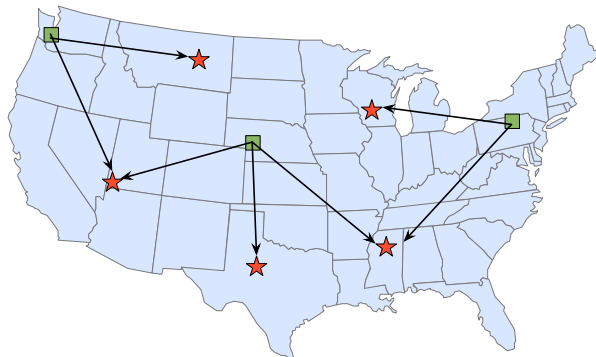
## Performance Evaluation

- ▶ Transportation problem with **production facilities**  $\mathcal{I}$  manufacturing products  $\mathcal{P}^+$  for customers  $\mathcal{J}$ .



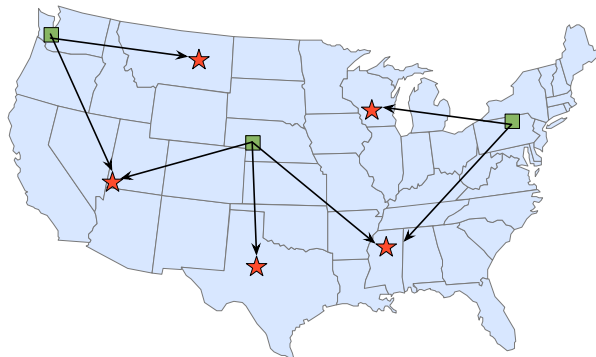
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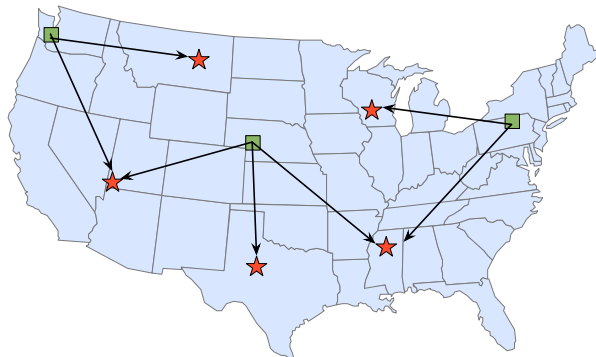
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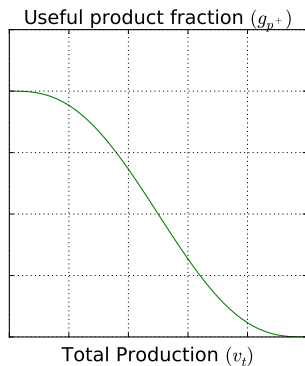
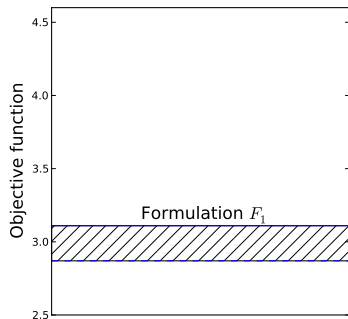
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- ▶ Facility **operations** follow known **production functions**.
- ▶ Facilities incur fixed, operating, transportation and penalty costs.

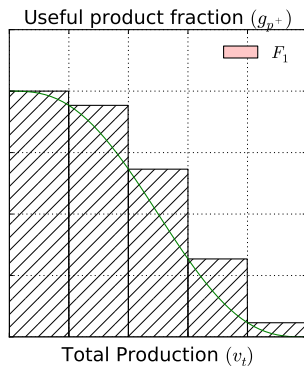
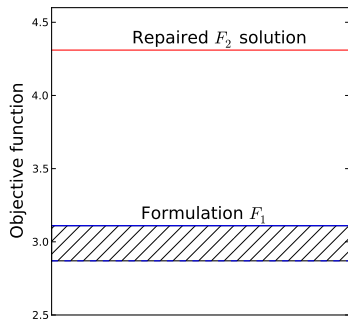




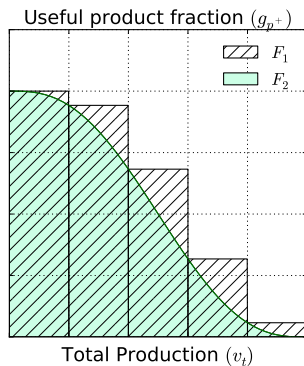
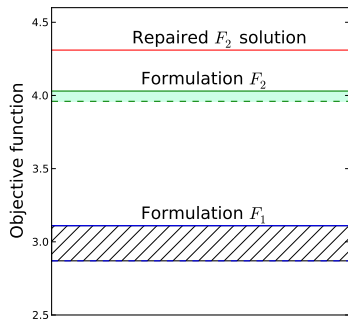
# Accuracy



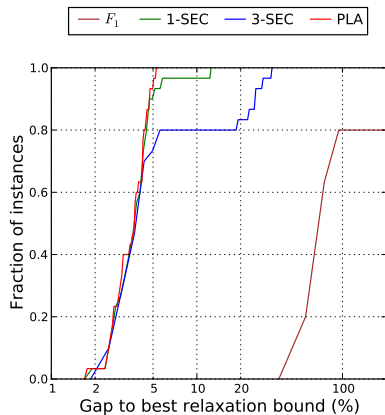
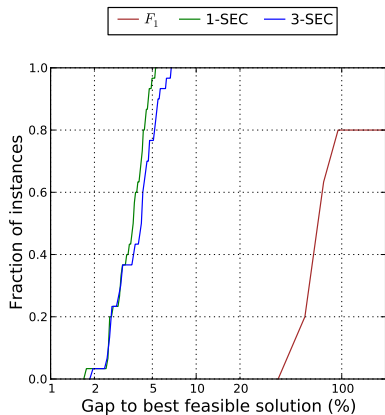
# Accuracy

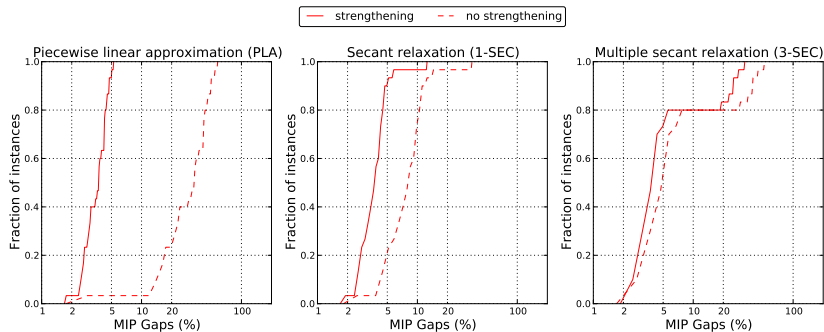


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# Formulations





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Thats all folks!

